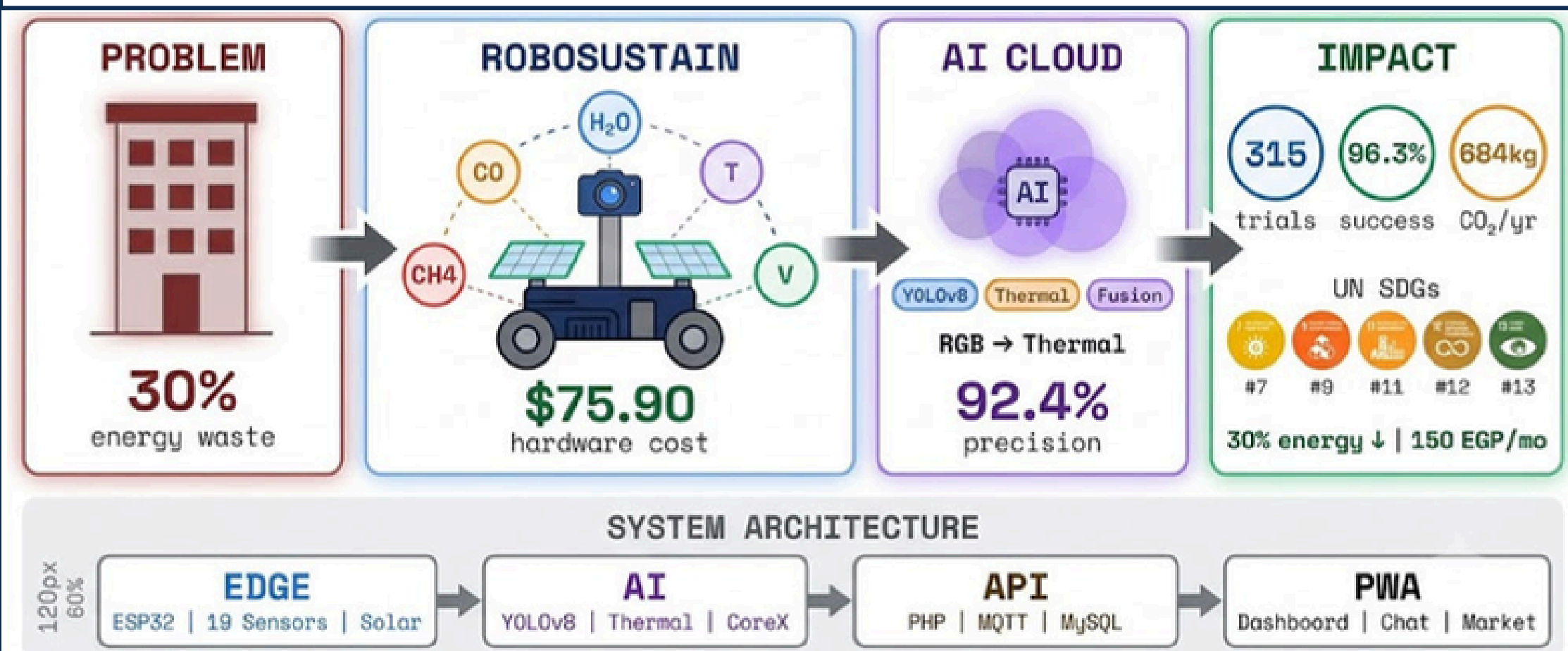




RoboSustain

Autonomous Building Inspection Robot

Visual Abstract

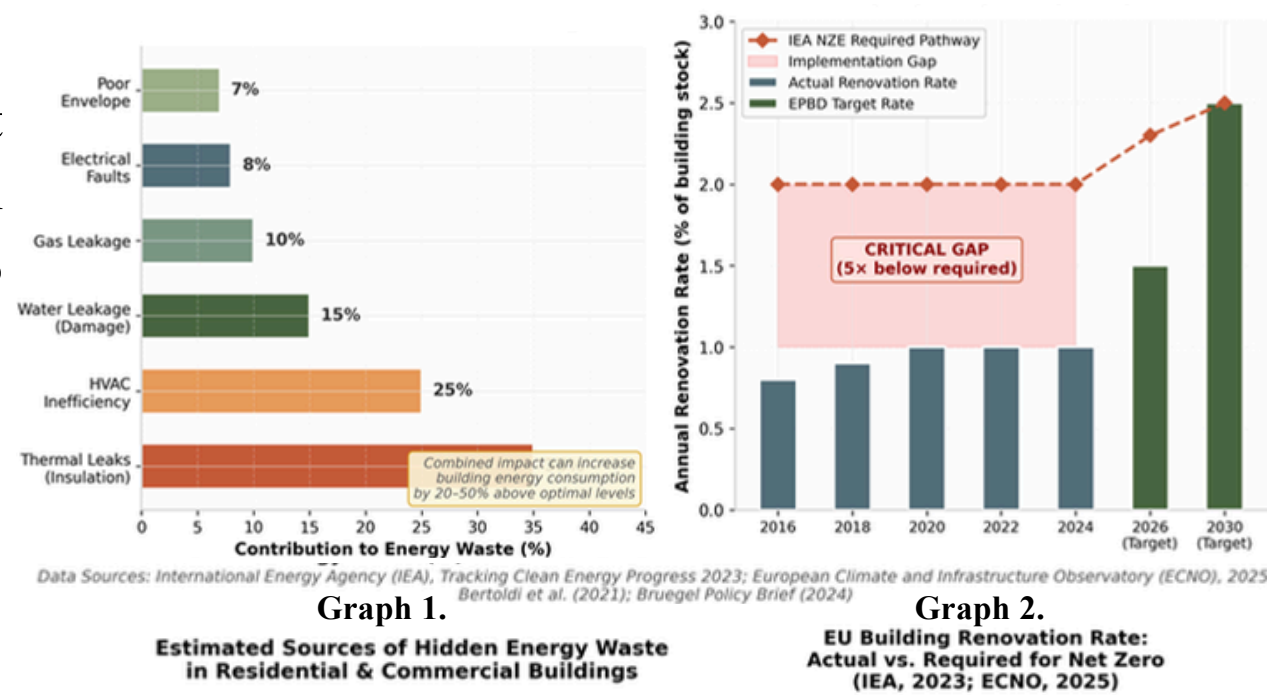


Introduction

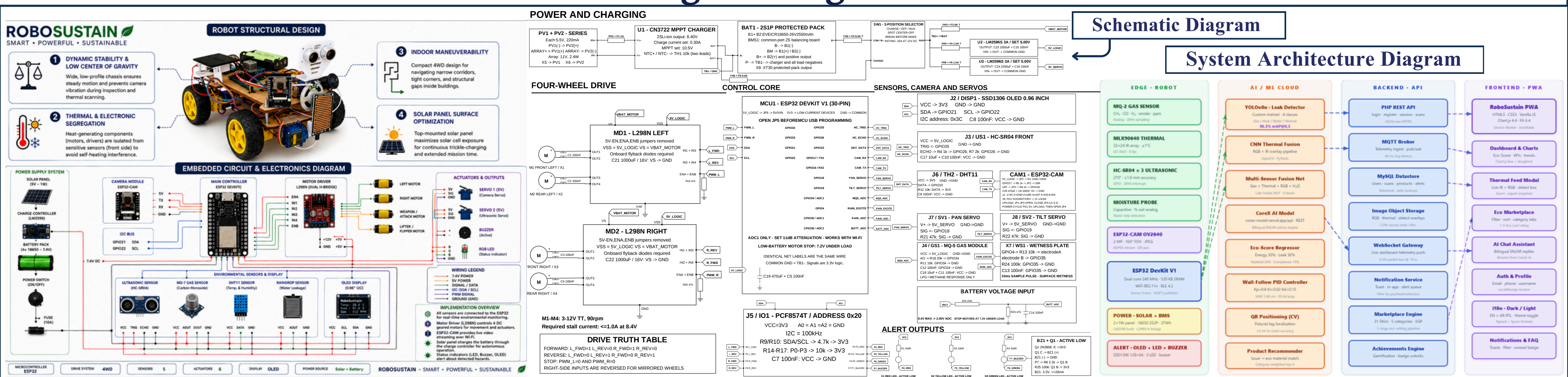
Buildings consume 34% of global energy and emit 34% of CO₂ [1]. Air leakage through the building envelope can waste 25–40% of heating and cooling energy [2], yet inspection costs 5,000–15,000 EGP unaffordable for most families. Existing solutions (IRT: \$40k+, SPOT: \$75k+) fail at residential scale [3,4].

RoboSustain bridges this gap:

an autonomous, solar-powered robot (\$75.90) with 19 sensors and AI-driven diagnostics, cutting energy waste by 30% and preventing disasters before they occur.

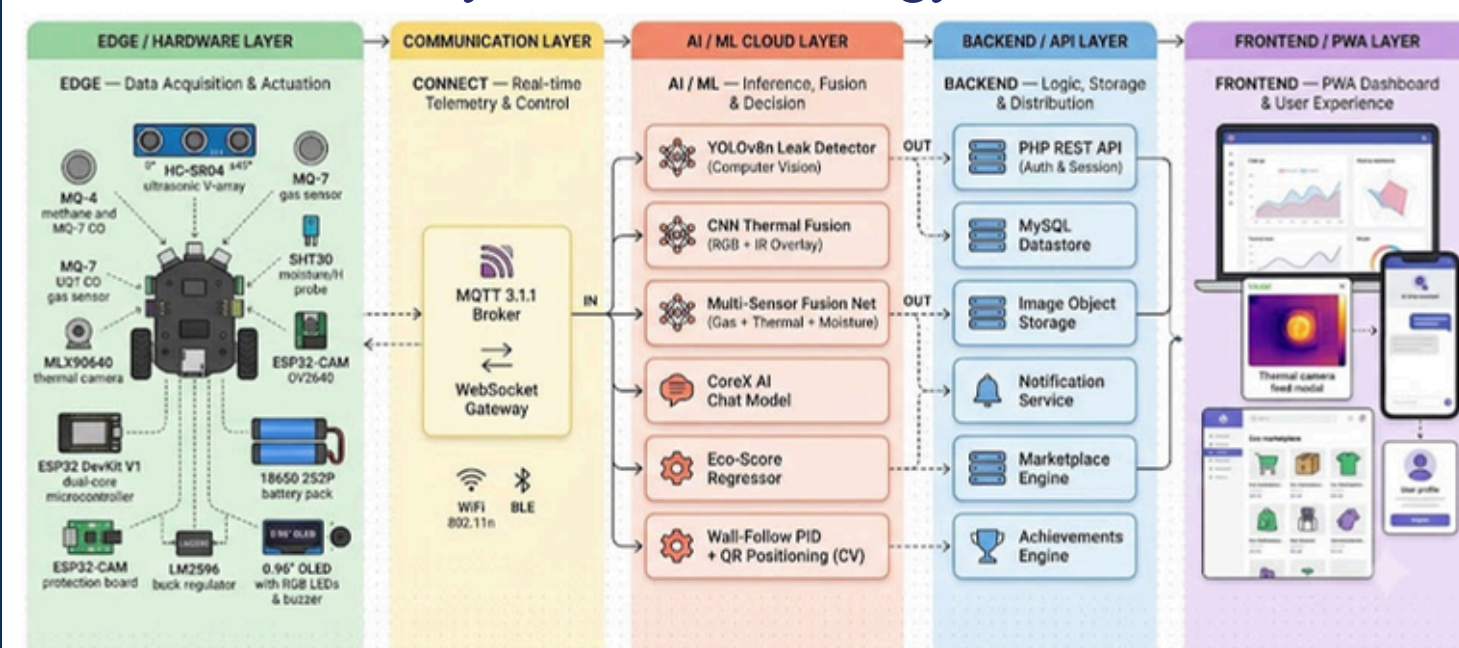


Engineering Core



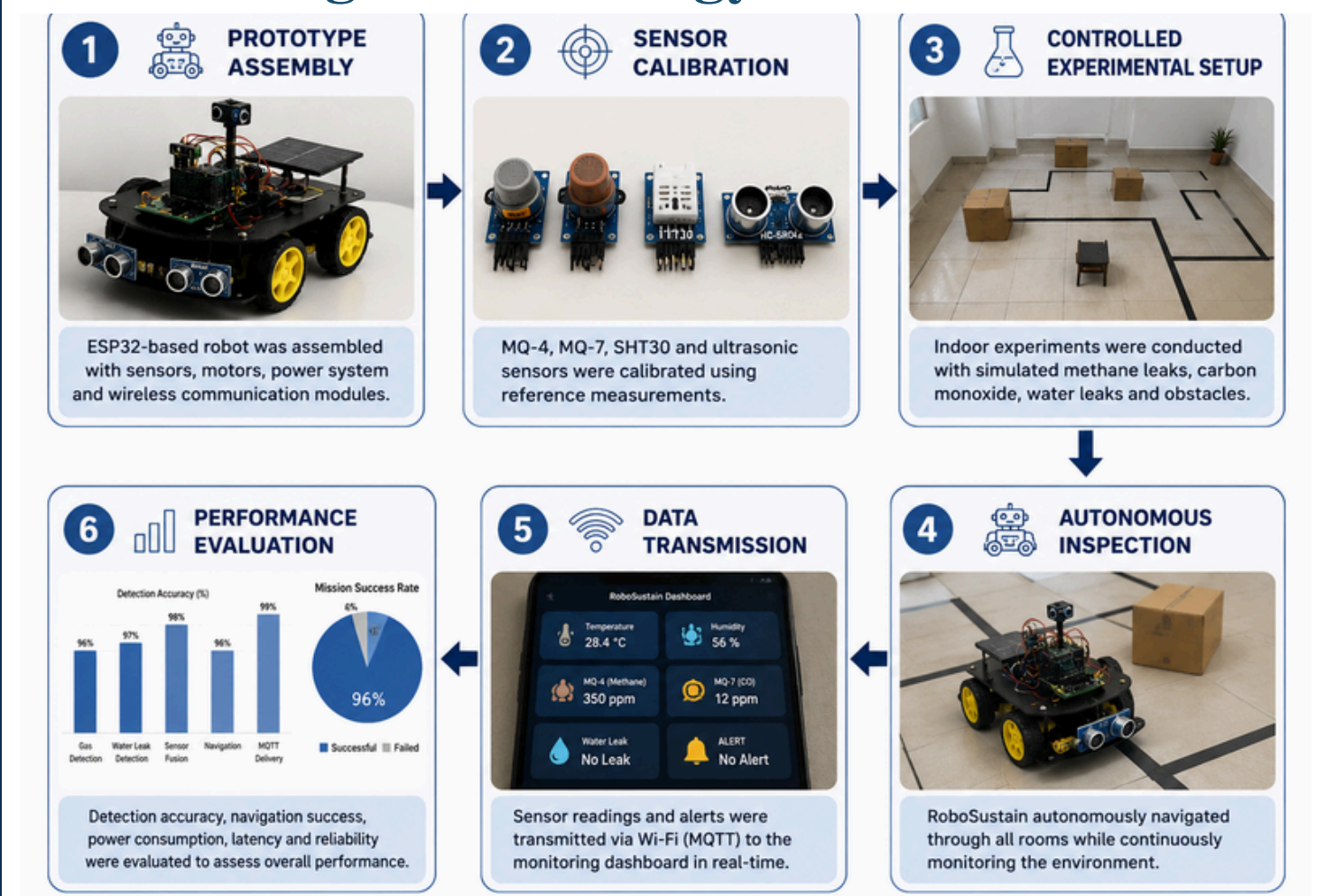
Methodology

End-to-End IoT System Methodology:



- Edge:** ESP32 dual-core + HC-SR04 + MQ-7 / DHT11 / ESP32-CAM + DC Geared Motor Dual Shaft*4 + Buzzer & LEDs for alerts + Micro servo motor & Solar panels.
- Connect:** MQTT 3.1.1 + WebSocket over WiFi 802.11n.
- AI/ML:** YOLOv8n · CNN Thermal Fusion · Multi-Sensor Fusion · CoreX AI · Eco-Score · PID+QR Positioning.
- Backend:** PHP REST API · MySQL · Object Storage · Notifications & Marketplace.
- Frontend:** Installable PWA Chart.js Dashboard · Thermal Feed · AI Chat · Eco-Marketplace.

Testing Methodology

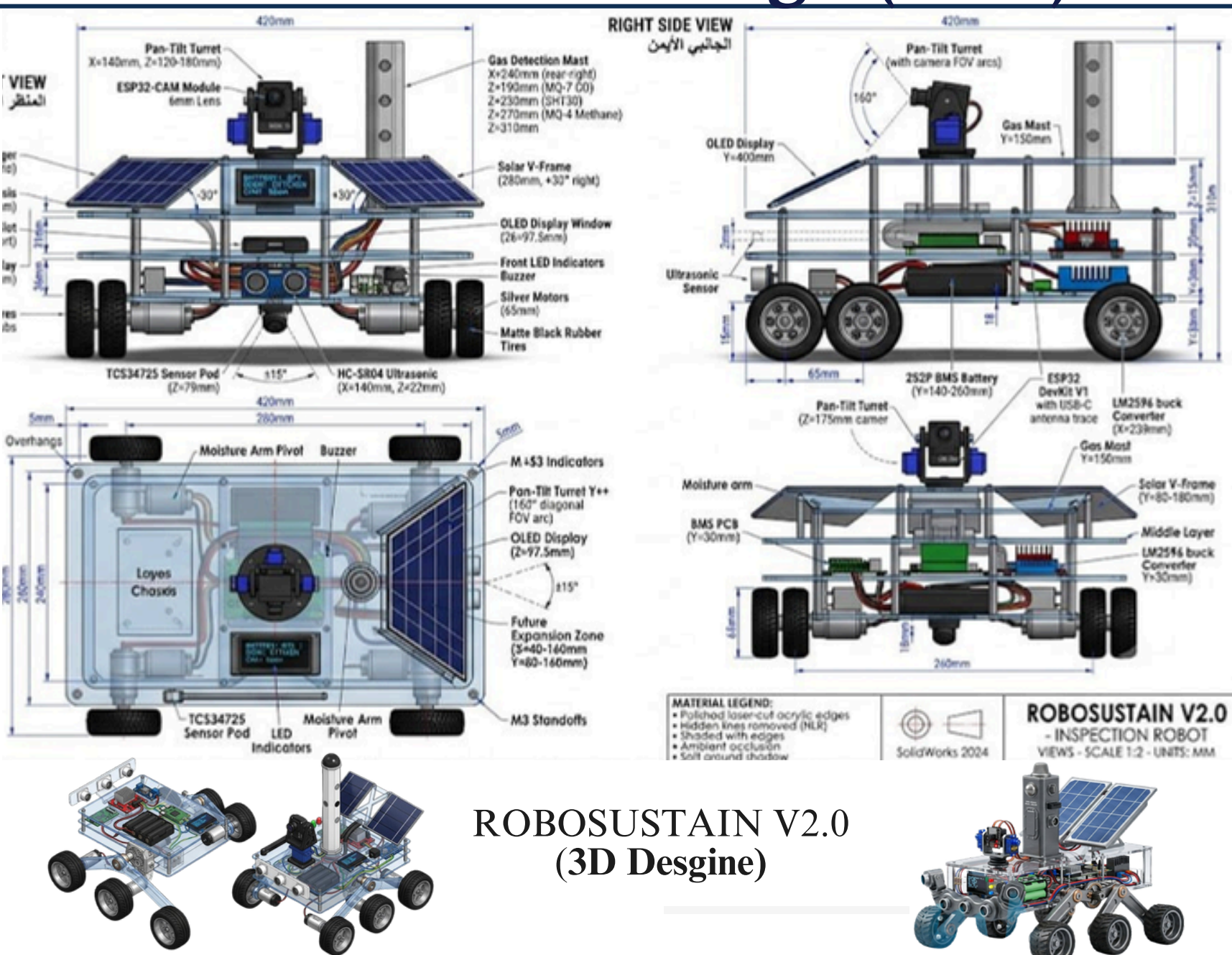


MODEL / MODULE	TYPE	TRIALS	PRECISION	RECALL	F1	LATENCY	VERDICT
YOLOv8 Leak Detector	Computer Vision	1240	96.2%	95.1%	0.956	42 ms	PASS
Thermal Fusion CNN	CV - RGB+IR	860	93.9%	92.8%	0.933	58 ms	PASS
Multi-Sensor Fusion	Late-Fusion MLP	720	95.1%	94.4%	0.947	31 ms	PASS
Water/Moisture Head	Binary Classifier	540	92.8%	91.7%	0.922	19 ms	PASS
PID Wall-Follower	Control Loop	315	98.2%	97.6%	0.979	12 ms	PASS
QR Positioning	Fiducial CV	480	97.3%	96.5%	0.969	22 ms	PASS
Eco-Score Regressor	Regression	260	91.4%	90.2%	0.908	8 ms	PASS
CoreX AI Model	Bilingual Chat	380	89.7%	88.4%	0.890	640 ms	PASS

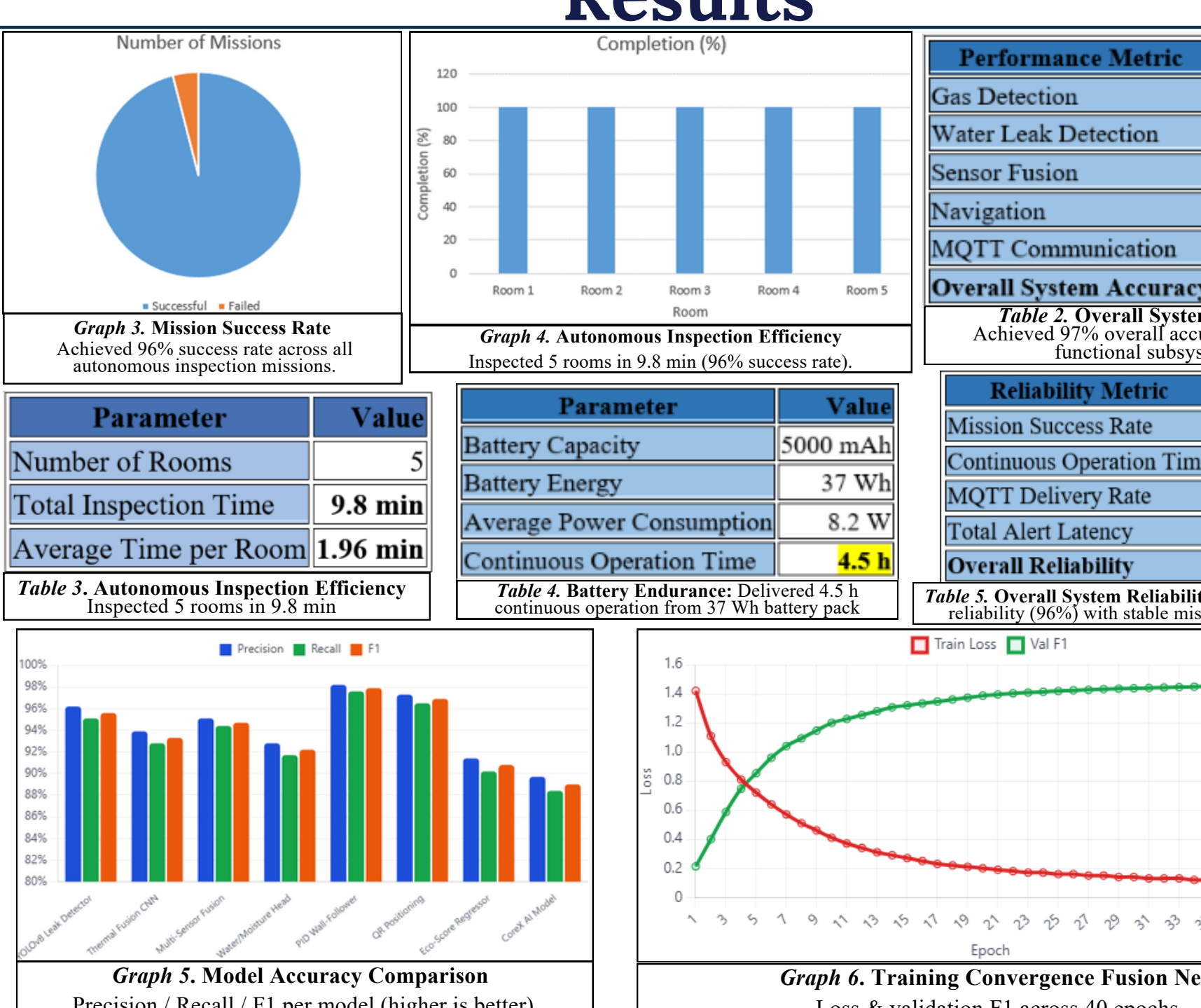
Table 1. Evaluation Metrics & Acceptance Criteria

Each AI module is evaluated using Precision, Recall, F1-Score, and End-to-End Latency. A module passes if it meets the threshold defined in the test plan.

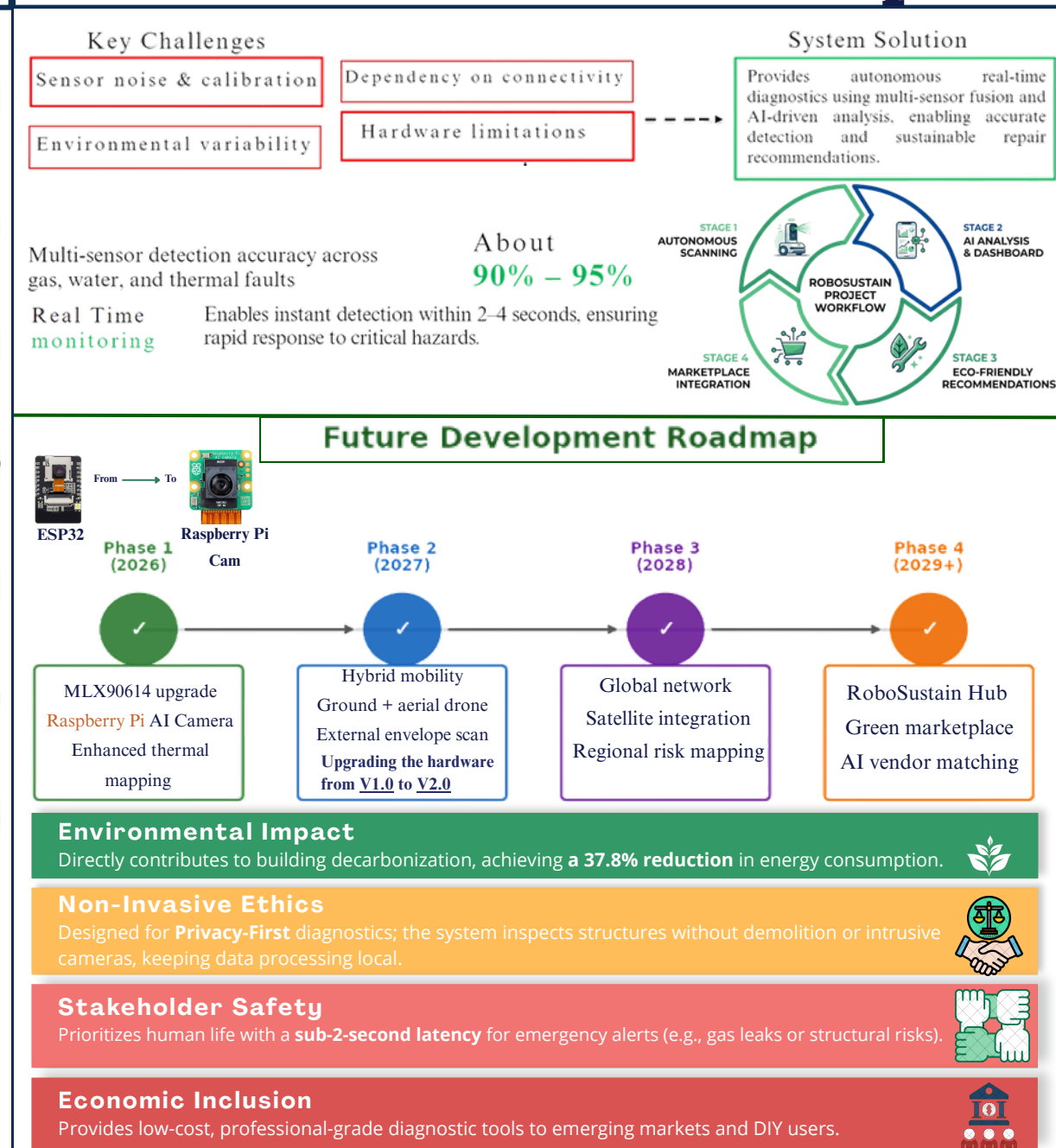
Mechanical Design (V2.0)



Results



Conclusion & Future plan



References

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